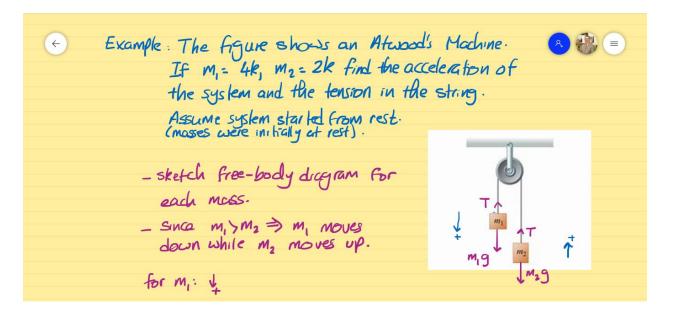
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Chapter 4:Dynamics: Newton's Laws of Motion

Lecture 4 (First Sem 20/21) The University of Jordan/Physics Department Prof. Mahmoud Jaghoub أ.د. محمود الجاغوب



$$\alpha = (\frac{m_1 - m_2}{m_1 + m_2})g = \frac{2}{6}g = \frac{1}{3}g \text{ m/s}^2$$

Substitute for a in 1) >

$$= \frac{M_1(M_1+M_1) + M_1(M_1-M_1)}{M_1+M_2} g$$

$$=\frac{2m_1m_2}{m_1+m_2}g=2\frac{8}{6}g=\frac{8}{3}g$$
 Newton.

Example

From GianColitextbook



$$F_{T} = \frac{1}{2} \frac{1}{mg} \frac{1}{\sqrt{1000}}$$
Special

F₁ F₁

FIGURE 4-24 Example 4-14.

CONCEPTUAL EXAMPLE 4-14 The advantage of a pulley. A mover is trying to lift a piano (slowly) up to a second-story apartment (Fig. 4-24). He is using a rope looped over two pulleys as shown. What force must be exert on the rope to slowly lift the piano's 1600-N weight?

RESPONSE The magnitude of the tension force F_T within the rope is the same at any point along the rope if we assume we can ignore its mass. First notice the forces acting on the lower pulley at the piano. The weight of the piano (= mg) pulls down on the pulley. The tension in the rope, looped through this pulley, pulls up troice, once on each side of the pulley. Let us apply Newton's second law to the pulley-piano combination (of mass m), choosing the upward direction as positive:

$$2F_{\rm T}-mg=ma.$$

To move the piano with constant speed (set a=0 in this equation) thus requires a tension in the rope, and hence a pull on the rope, of $F_T=mg/2$. The piano mover can exert a force equal to half the piano's weight.

NOTE We say the pulley has given a mechanical advantage of 2, since without the pulley the mover would have to exert twice the force.

Note: we need to exert a force equals half the weight of the object (when $\alpha = 0$).

Example Find a and Ti.

m,= 2kg, m2 = 3kg.

For
$$m_i: \rightarrow +$$

 $T_i = m_i \alpha - 0$

For M2: ->+

$$T_2 - T_1 = m_2 \alpha - 2$$

$$(1+2) \Rightarrow T_2 = (m_1 + m_2) c_1$$

$$c_1 = \frac{T_2}{m_1 + m_2} = \frac{20}{2+3} = \frac{4}{2} = \frac{4}{3} = \frac{4$$

$$M_1$$
 M_2
 M_2
 M_2
 M_3
 M_4
 M_2
 M_4
 M_5
 M_6
 M_6

Newtons

Smooth

Surface. (No Friction).

For
$$m_i: \rightarrow +$$

$$T_i = m_i \alpha - 0$$

For M2: ->+

$$Q = \frac{T_2}{m_1 + m_2} = \frac{20}{2+3} = \frac{4}{4} \frac{m/s^2}{s^2}$$

using 1) = T1 = (2)(4) = 8 Newton.

Also note + N,-M,g=0 > N,=M,g.

† N2-m2g=0 > N2=M2g-

← Friction

Objects look smooth to the noted eye. But under a microscope objects have irregularities.

As the surfaces which are in contact move against each other the irregularities impede the motion.

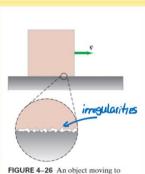
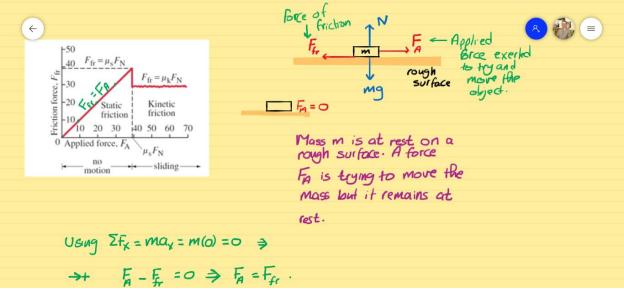


FIGURE 4–26 An object moving to the right on a table. The two surfaces in contact are assumed smooth, but are rough on a microscopic scale.







As long as the mass is stationary > FA = Far # This is given by the straight line in the figure. # The force of friction that acts while the object is at 10 20 30 REST is called State Friction and I shall refer to it as f_s . kinetic friction Static friction fs , fs, max # Whe the object is on the vege of moving (about to move) But still has not moved we have the maximum possible value of static friction called maximum static friction f_{s,max} = Ms Ne Normal force , Ms = f_{s,max} coefficient of static friction (dimensionless 1.e has no units)

 (\leftarrow) # As soon as the object starts moving > we have kinetic friction (fx)



$$f_k = \mu_k$$
 N normal force

coefficient of kinetic friction (has no units)

Note that fr < fs, max. > MR < Ms

when the object starts moving the contact between the inequalities is mostly at the tips which reduces the surface area of contact and hence reduces the force of friction.

- NOTE: MS > MK
 - # Ms and Mx depend on the nature of the surfaces in contact.
 - # 1/s and Uk don't depend on the surface area of the two surfaces.

Surfaces	Coefficient of Static Friction, μ_s	Coefficient of Kinetic Friction, μ_k
Wood on wood	0.4	0.2
Ice on ice	0.1	0.03
Metal on metal (lubricated)	0.15	0.07
Steel on steel (unlubricated)	0.7	0.6
Rubber on dry concrete	1.0	0.8
Rubber on wet concrete	0.7	0.5
Rubber on other solid surfaces	1-4	1
Teflon® on Teflon in air	0.04	0.04
Teflon on steel in air	0.04	0.04
Lubricated ball bearings	< 0.01	< 0.01
Synovial joints (in human limbs)	0.01	0.01

Example: find the force of Friction in each of the following cases: (all objects are at REST)

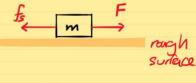


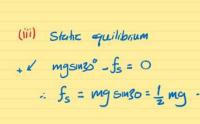
(i) No force is trying to move object along x-axis > fs=0. Note: fs only arises when object tries

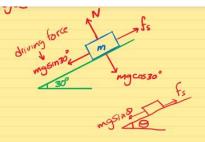
to more due to an acting force

(ii) static equilibrium >+ F-fs=0 > F=fs this force tries to move the object.









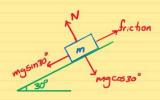


- (iv) In the figure m=4kg, Ms=0.5 and Hz=0.1.
- (a) Is the object going to move?
- (b) Find a.
- (move)

 (a) For the object to slide

 down the inclined plane >

 mgsin 30° > fs,max.

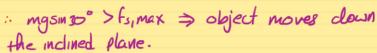


+R N-mg cos 30° =0 N=mg/3

mgsm30°=4×10 ×1/2 = 20 Newbons.

f_{s,max} = N₅ N = 6.5)(4×10×13) = 1013 Newtons.

f_{s,max} = \$\mu_{\mathbf{S}} N = (6.5)(4 \times 10 \times \frac{1}{2}) = 10 (3) Newtons.





To find the occeleration apply Newton's 2nd law

 $f_{k} = \mu_{k} N$ $m_{qsinso} - \mu_{k} N = ma$

$$\alpha = \frac{mgsm20 - \mu_k N}{m}$$

$$\alpha = \frac{20 - 0.1 \times 4 \times 10 \times 15}{4} = \frac{16.53}{4} \sim 4.1 \text{ m/s}^2$$